

## A Study on the Influence of Cutting Parameters Like Thrust Force and Torque in Drilling Operations by Simulation

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### ABSTRACT:

This paper discusses the influence of cutting parameters in drilling of glass fiber reinforced composites, Mild Steel and Aluminum alloy. The experiments are conducted to study the effect of point angle, spindle speed and feed rate on thrust force and torque using HSS twist drills. This paper presents a mathematical model for correlating the interactions of drilling parameters and their effects on thrust force and torque. The optimum value of cutting parameters is also determined to get minimum value of thrust force and torque. In thesis, diameter of drilling cutting tool is 12mm, 8mm. theoretical calculations are done to calculate thrust force and torque. The assembly of work piece and tool are modeled in Pro/Engineer. The input parameters considered are point angle  $118^\circ$  and  $120^\circ$ , tool diameter, spindle speed, feed rate and materials. Different combinations of the above parameters are considered to get the minimum value of thrust force and torque. Structural analysis is done on the assembly to verify the stresses for different materials Mild Steel, Aluminum alloy and composite material E Glass Epoxy. Analysis is done in Ansys.

### INTRODUCTION:

Drilling is a cutting process that uses a drill bit to cut or enlarge a hole of circular cross-section in solid materials. The drill bit is a rotary cutting, often multipoint. The bit is pressed against the workpiece and rotated at rates from hundreds to thousands of revolutions per minute. This forces the cutting edge against the work piece, cutting off chips (swarf) from the hole as it is drilled. Small to medium-sized drilling rigs are mobile, such as those used in mineral exploration drilling, blast-hole, water wells and

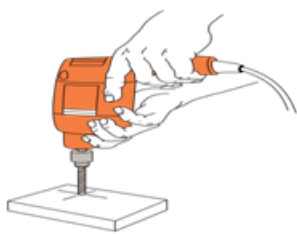
environmental investigations. Larger rigs are capable of drilling through thousands of metres of the Earth's crust, using large "mud pumps" to circulate drilling mud (slurry) through the drill bit and up the casing annulus, for cooling and removing the "cuttings" while a well is drilled. Hoists in the rig can lift hundreds of tons of pipe. Other equipment can force acid or sand into reservoirs to facilitate extraction of the oil or natural gas; and in remote locations there can be permanent living accommodation and catering for crews (which may be more than a hundred). Marine rigs may operate thousands of miles distant from the supply base with infrequent crew rotation or cycle.



### DRILL:

A **drill** is a tool fitted with a cutting tool attachment or driving tool attachment, usually a drill bit or driver bit, used for boring holes in various materials or fastening various materials together with the use of fasteners. The attachment is gripped by a chuck at one end of the drill and rotated while pressed against the target material.

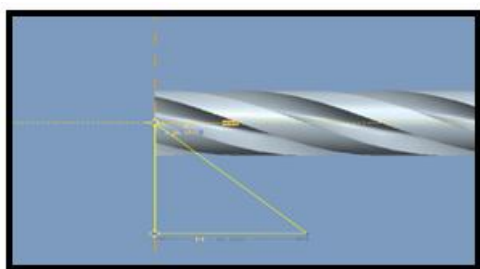
The tip, and sometimes edges, of the cutting tool does the work of cutting into the target material. This may be slicing off thin shavings (twist drills or auger bits), grinding off small particles (oil drilling), crushing and removing pieces of the work piece (SDS masonry drill), countersinking, counter boring, or other operations. Drills are commonly used in woodworking, metalworking, construction and do-it-yourself projects. Specially designed drills are also used in medicine, space missions and other applications. Drills are available with a wide variety of performance characteristics, such as power and capacity.



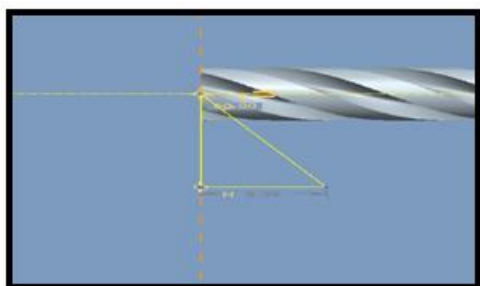
## MODELS OF DRILLING TOOL AND WORKPIECE

**DIAMETER – 8mm**

**118° ANGLE CUT**

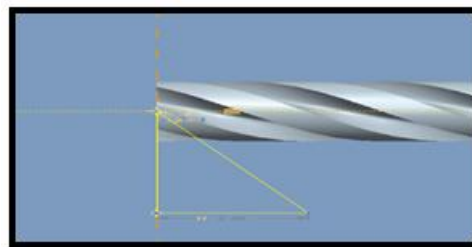


**120° ANGLE CUT**

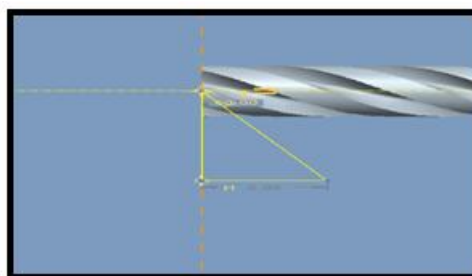


**DIAMETER -12mm**

**118° ANGLE CUT**



**120° ANGLE CUT**



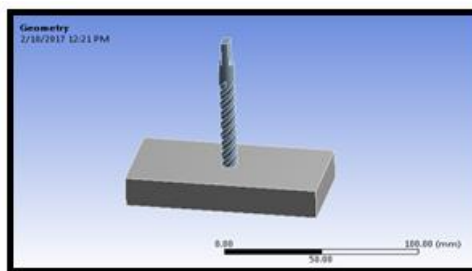
## STRUCTURAL ANALYSIS OF DRILLING TOOL

**8mm DIAMETER - 118° ANGLE**

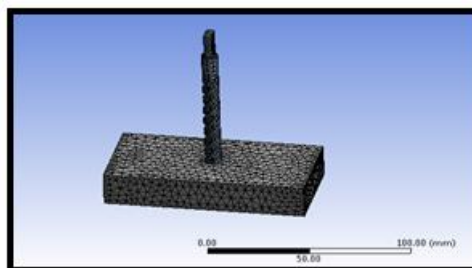
**MATERIAL – ALUMINIUM**

**FORCE – 600 N**

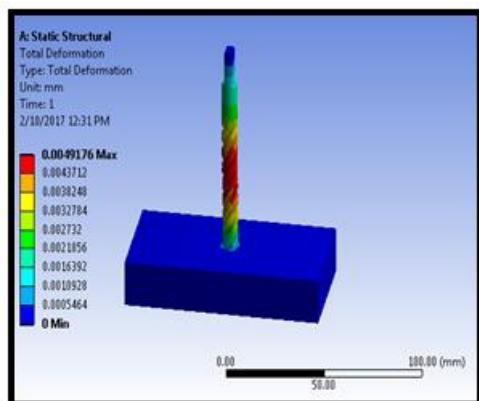
## IMPORTED MODEL



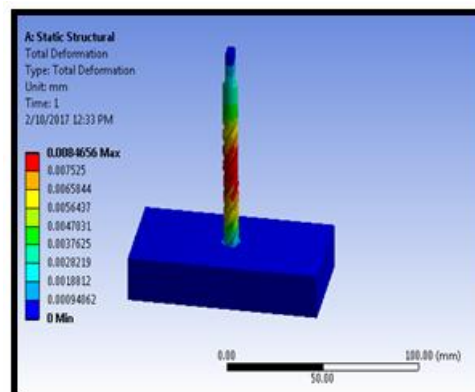
## MESHED MODEL



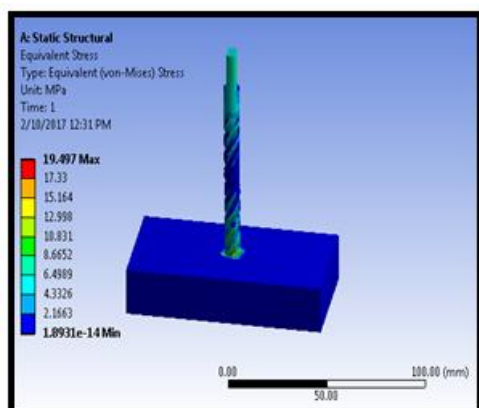
### TOTAL DEFORMATION



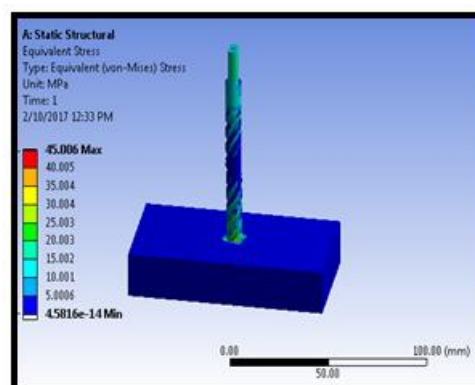
### TOTAL DEFORMATION



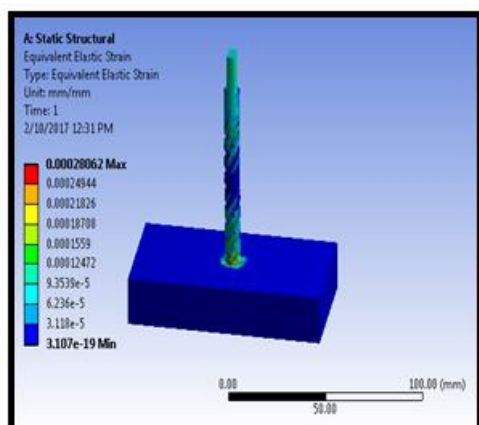
### STRESS



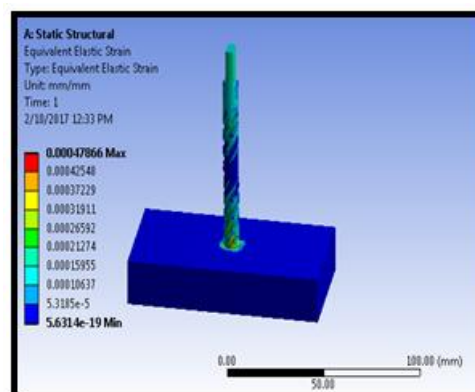
### STRESS



### STRAIN



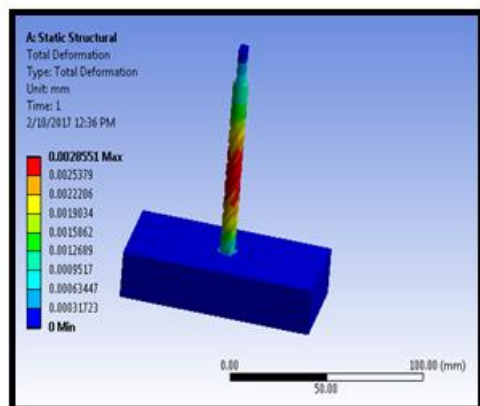
### STRAIN



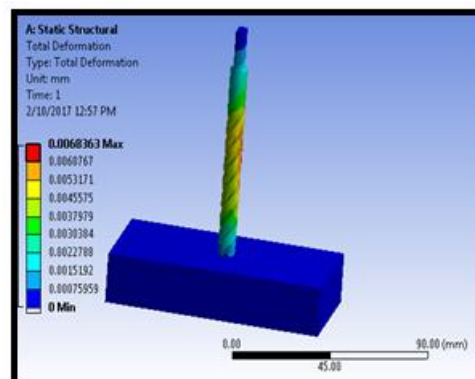
**MATERIAL –TITANIUM ALLOY**  
**FORCE – 1400 N**

**MATERIAL –E GLASS EPOXY**  
**FORCE – 416 N**

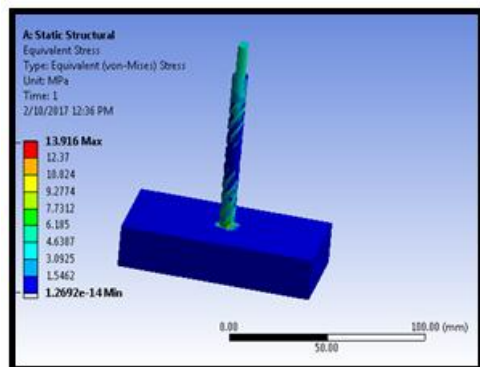
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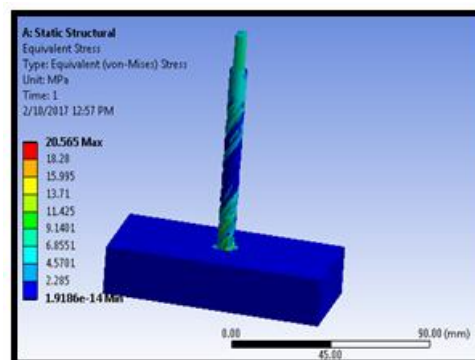
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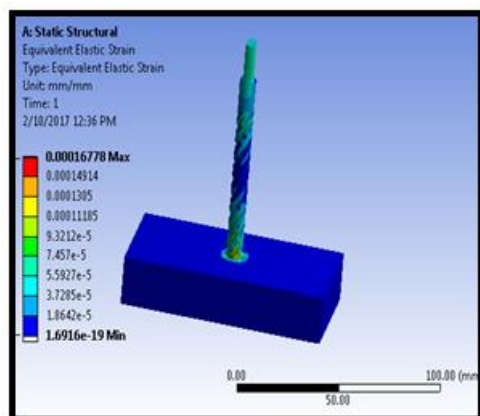
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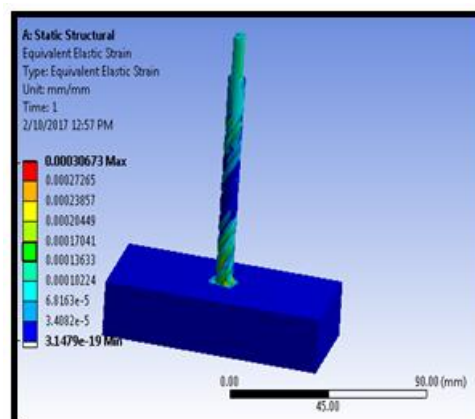
## STRESS



## STRAIN



## STRAIN

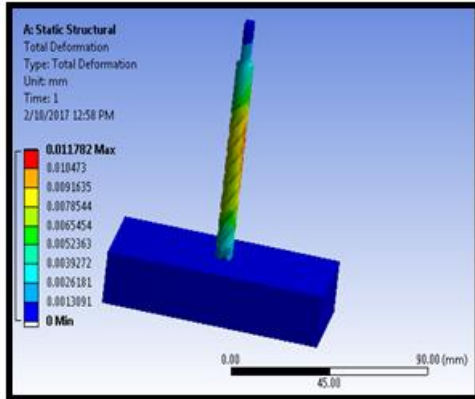


**8mm DIAMETER - 120° ANGLE**  
**MATERIAL –ALUMINUM**  
**Force – 600 N**

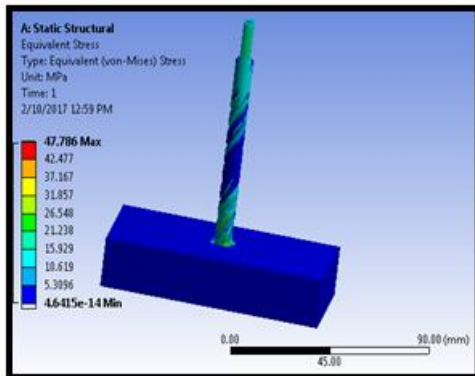
**MATERIAL –TITANIUM ALLOY**  
**FORCE – 1400 N**



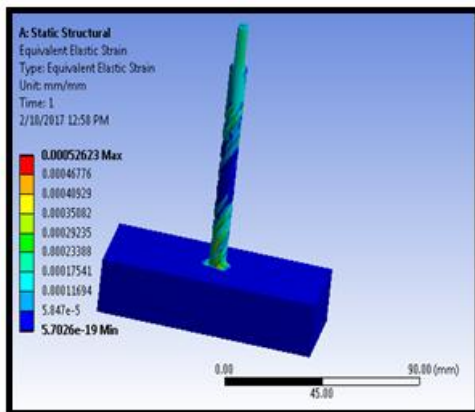
### TOTAL DEFORMATION



### STRESS

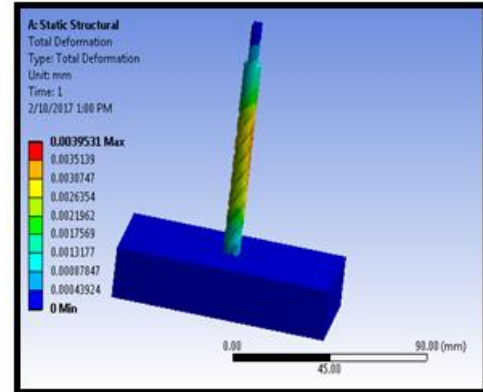


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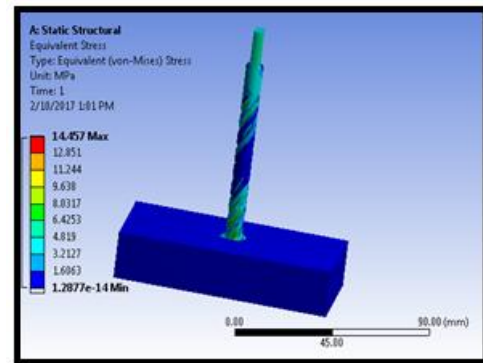


**MATERIAL –E GLASS EPOXY  
 FORCE – 416 N**

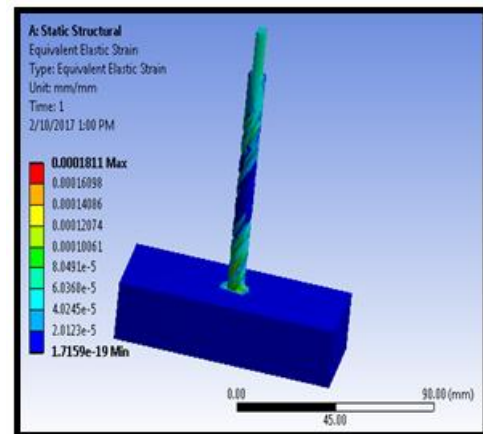
### TOTAL DEFORMATION



### STRESS

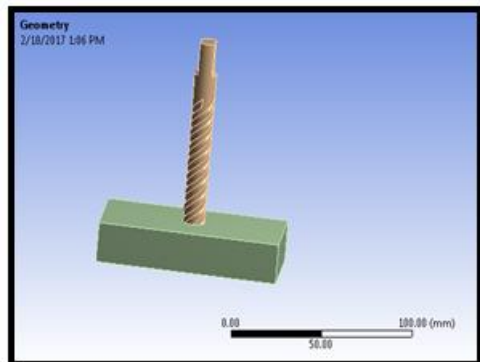


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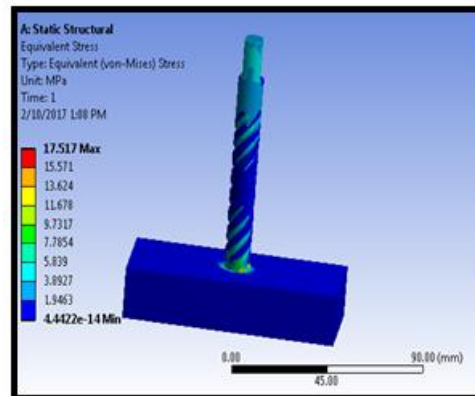


**12mm DIAMETER - 118° ANGLE  
 MATERIAL –ALUMINIUM  
 FORCE – 900 N**

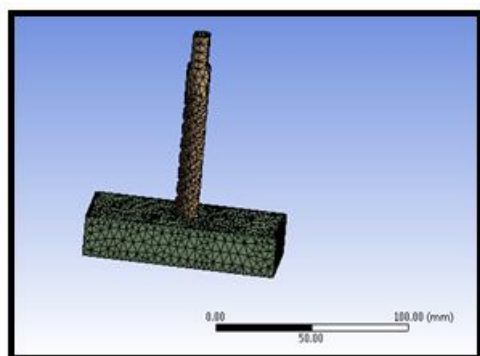
## IMPORTED MODEL



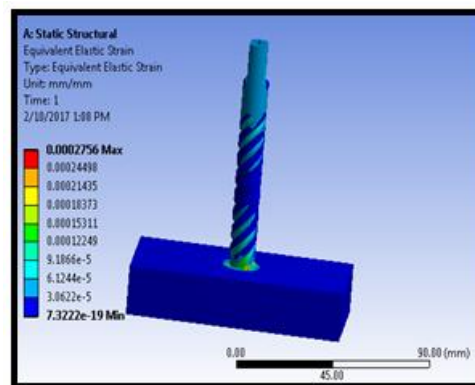
## STRESS



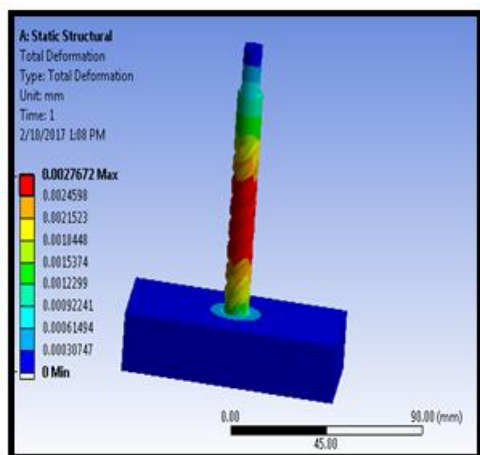
## MESHED MODEL



## STRAIN

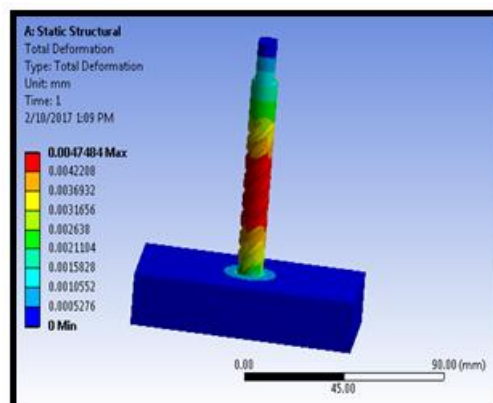


## TOTAL DEFORMATION

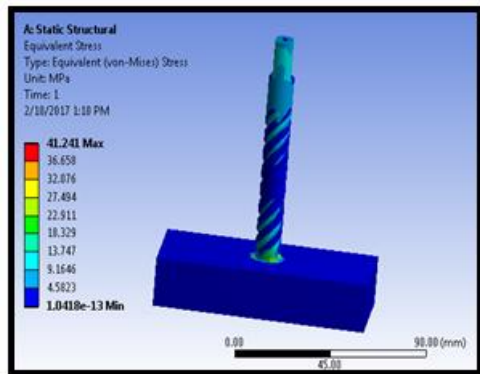


## MATERIAL –TITANIUM ALLOY FORCE – 2100 N

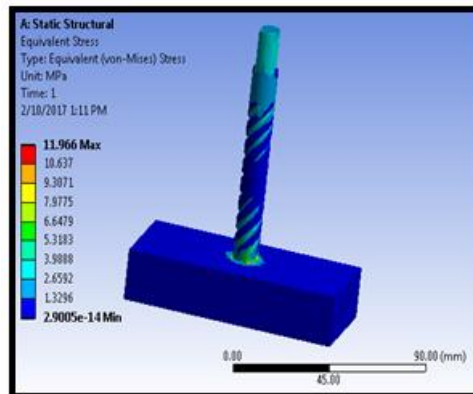
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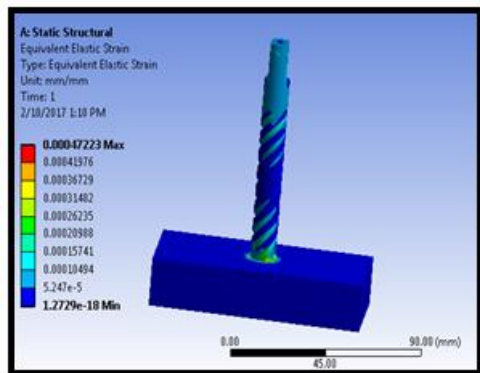
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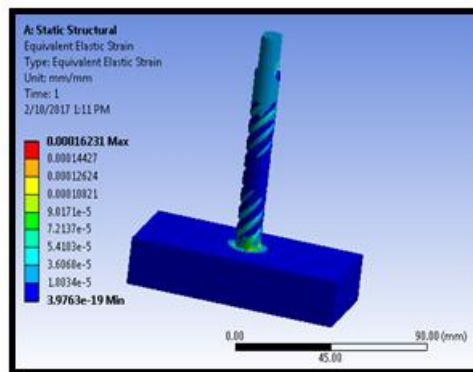
## STRESS



## STRAIN



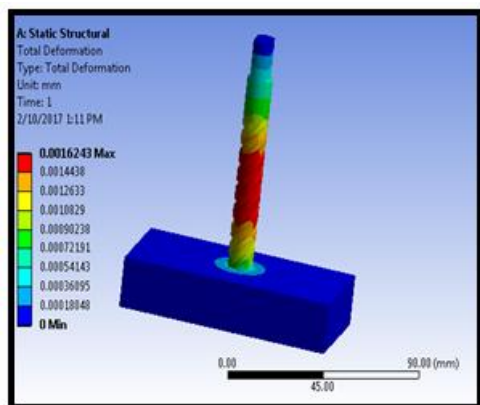
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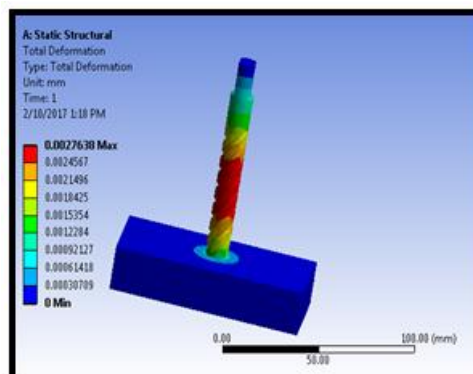
**MATERIAL –E GLASS EPOXY  
 FORCE –624 N**

**12 MM DIAMETER - 120° ANGLE  
 MATERIAL –ALUMINUM  
 FORCE – 900 N**

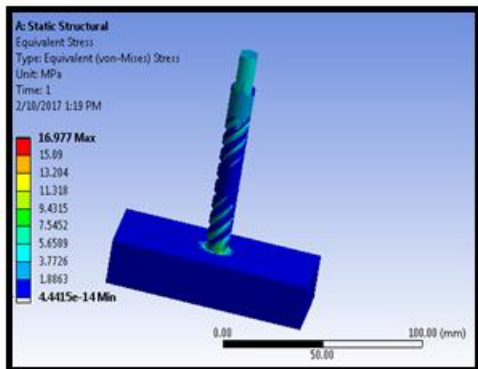
## TOTAL DEFORMATION



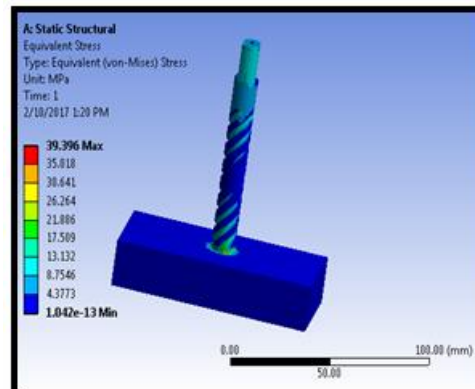
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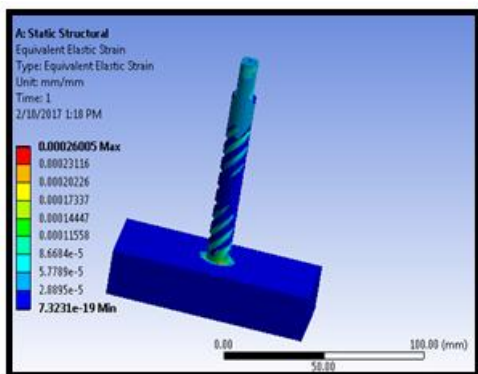
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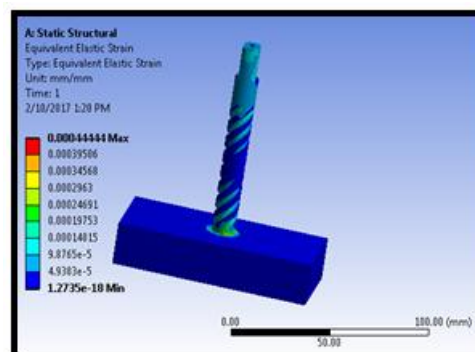
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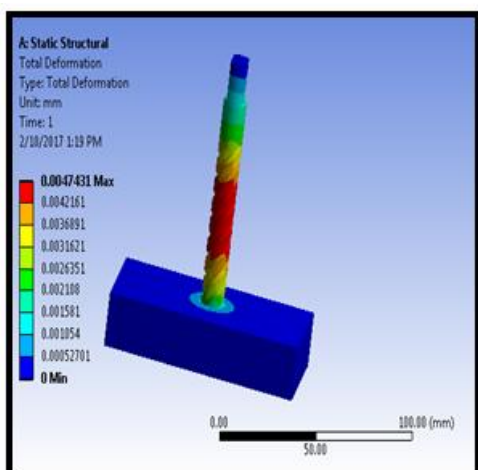
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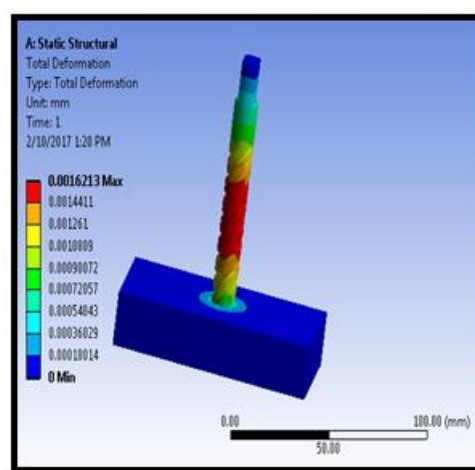
**MATERIAL –TITANIUM ALLOY**  
**FORCE – 2100 N**

**MATERIAL –E GLASS EPOXY**  
**FORCE – 624 N**

## TOTAL DEFORMATION

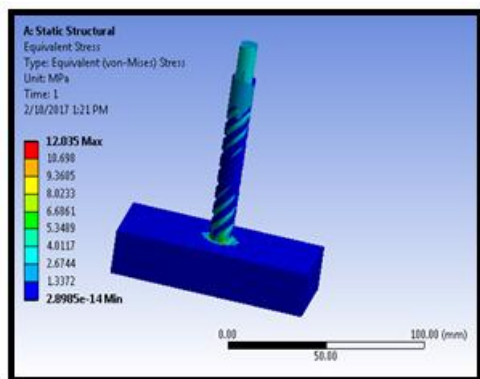


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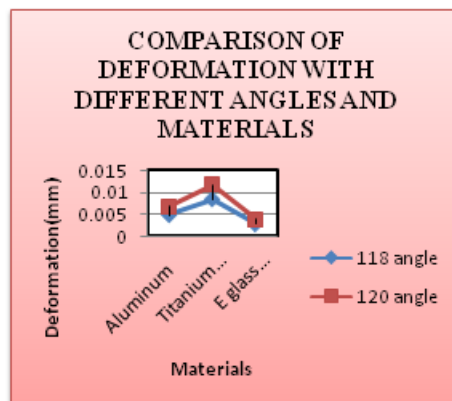




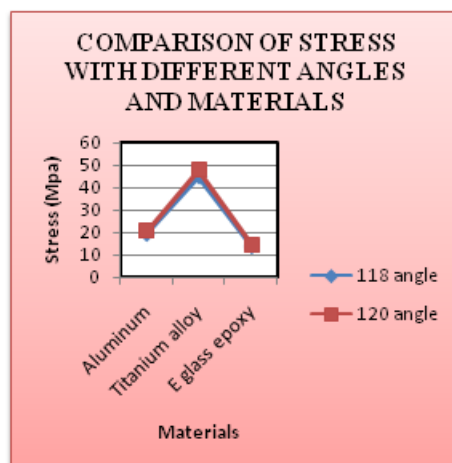
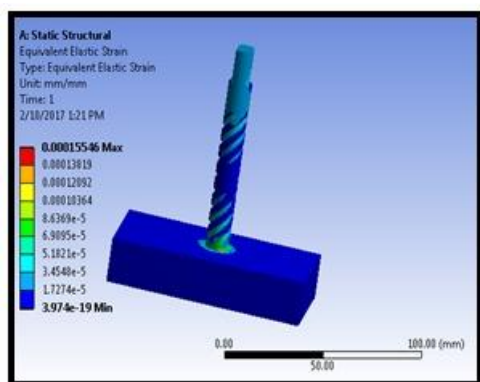
## STRESS



## GRAPHS



## STRAIN

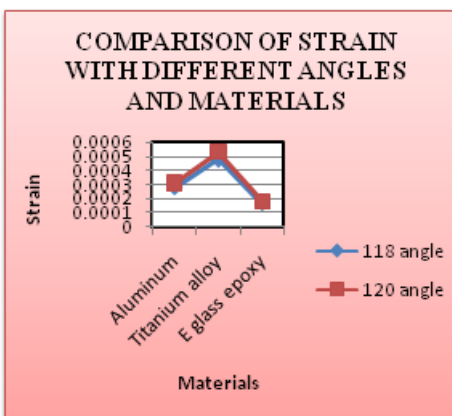


## RESULTS & DISCUSSION

### STRUCTURAL ANALYSIS

#### 8 mm DIAMETER

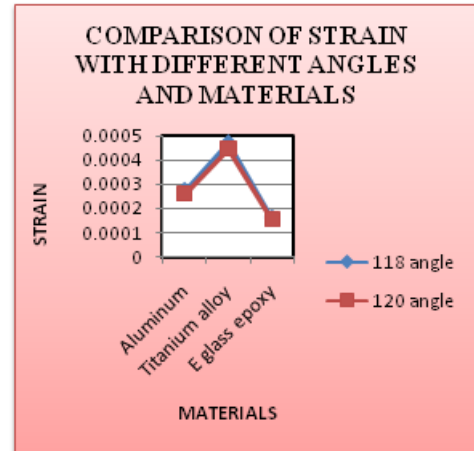
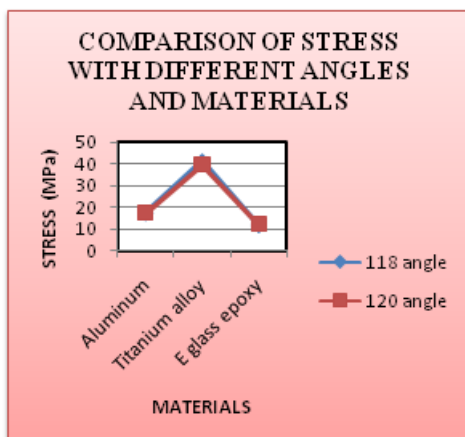
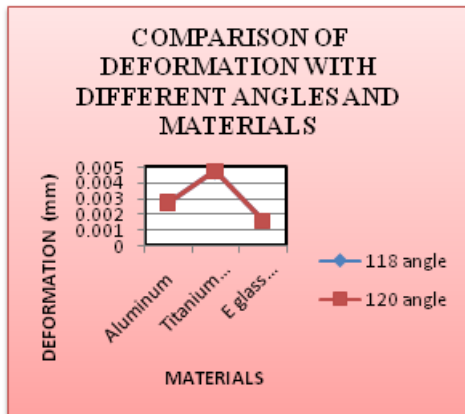
Angle s	Materials	Total deformati on (mm)	Stres s (MPa )	Strain
118 <sup>0</sup>	Aluminiu m	0.0049176	19.49 7	0.000280 62
	Titanium alloy	0.0084656	45.00 6	0.000478 66
	E glass epoxy	0.0028551	13.91 6	0.000167 78
120 <sup>0</sup>	Aluminiu m	0.0068363	20.56 5	0.000306 73
	Titanium alloy	0.011782	47.78 6	0.000526 23
	E glass epoxy	0.0039531	14.45 7	0.000181 1



## 12 mm DIAMETER

Angle s	Materials	Total deformati on (mm)	Stres s (MPa )	Strain
118 <sup>0</sup>	Aluminiu m	0.0027672	17.51 7	0.000275 6
	Titanium alloy	0.0047484	41.24 1	0.000472 23
	E glass epoxy	0.0016243	11.96 6	0.000162 31
120 <sup>0</sup>	Aluminiu m	0.0027638	16.97 7	0.000260 05
	Titanium alloy	0.0047431	39.39 6	0.000444 4
	E glass epoxy	0.0016213	12.03 5	0.000155 46

## GRAPHS



## CONCLUSION:

In this thesis, drilling operations are conducted on the carbon fiber reinforced pieces with 12mm and 8mm diameter drills with 118<sup>0</sup> and 120<sup>0</sup> point angles with different cutting parameters. The cutting parameters are spindle speed – 1000rpm and 2500rpm, Feed – 0.2mm/rev for 8mm drill tool and 0.35mm/rev for 12mm drill tool. Cutting tool material is HSS. Forces are calculated using theoretical calculations. 3D modeling is done in Creo 2.0 and analysis is done in Ansys. Analysis is performed and the stresses, displacements are compared for three materials Aluminum, Titanium alloy and E Glass Epoxy. By observing the analysis results, the stresses and displacements are less for E Glass Epoxy than Aluminum and Titanium alloy. When compared the results between 118<sup>0</sup> and 120<sup>0</sup>, the deformation and stress values are less when 120<sup>0</sup> cutting tool is used.

## REFERENCES:

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9. Davim J.P, P. Reis and C.C. Antonio, " Experimental study of drilling glass fiber reinforced plastics (GFRP)

manufactured by hand lay-up," Composites Science and Technology 64, pp. 289-297, 2004.

10. Davim J.P, P. Reis and C.C. Antonio, "Drilling fiber reinforced plastics (FRPs) manufactured by hand lay-up: influence of matrix (Viapal VUP 9731 and ATLAC 382-05)," Journal of Materials Processing Technology, 155-156: 1828–1833. 2004.

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