Wireless Arm-Based Automatic Meter Reading & Control System (WAMRCS)

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ABSTRACT:
In this paper we discuss about Wireless ARM Based Automatic Meter Reading with control system (WAMRCS). This System is used with 32 bit ARM microprocessor for reading power consumption & communicates this data to the utility server for power data processing. GPRS networks are used for communication with utility server in two – way communication link. Power data is used for various purposes such as bill management, for measurement of static power parameters etc. Control systems contains relay circuit, used for disconnection power supply when consumer fails to pay electricity bill in due time. In this project automatic meter controlling systems is developing by the wireless communication system. the recent technology is that which can be used to develop the human resource easy by using the automation here we can check the current bill in our handset and also we can pay the bill in our present place only.

Introduction to Embedded Systems:
Embedded systems are electronic devices that incorporate microprocessors with in There implementations. The main purposes of the microprocessors are to simplify the system design and provide flexibility. Having a microprocessor in the device means that removing the bugs, making modifications, or adding new features are only matters of rewriting the software that controls the device. Or in other words embedded computer systems are electronic systems that include a microcomputer to perform a specific dedicated application. The computer is hidden inside these products. Embedded systems are ubiquitous.

Every week millions of tiny computer chips come pouring out of factories finding their way into our everyday products. Embedded systems are self-contained programs that are embedded within a piece of hardware. Whereas a regular computer has many different applications and software that can be applied to various tasks, embedded systems are usually set to a specific task that cannot be altered without physically manipulating the circuitry. Another way to think of an embedded system is as a computer system that is created with optimal efficiency, thereby allowing it to complete specific functions as quickly as possible.

BLOCK DIAGRAM:

ARM Microcontroller: LPC2148:
The LPC2141/42/44/46/48 microcontrollers are based on a 16-bit/32-bit ARM7TDMI-S CPU with real-time emulation and embedded trace support, that combine microcontroller with embedded high speed flash memory ranging from 32 kB to 512 kB. A 128-bit wide memory interface and unique accelerator
architecture enable 32-bit code execution at the maximum clock rate. For critical code size applications, the alternative 16-bit Thumb mode reduces code by more than 30% with minimal performance penalty. Due to their tiny size and low power consumption, LPC2141/42/44/46/48 are ideal for applications where miniaturization is a key requirement, such as access control and point-of-sale. Serial communications interfaces ranging from a USB 2.0 Full-speed device, multiple UARTs, SPI, SSP to I2C-bus and on-chip SRAM of 8kB up to 40kB, make these devices very well suited for communication gateways and protocol converters, soft modems, voice recognition and low end imaging, providing both large buffer size and high processing power. Various 32-bit timers, single or dual 10-bit ADC(s), 10-bit DAC, PWM channels and 45 fast GPIO lines with up to nine edge or level sensitive external interrupt pins make these microcontrollers suitable for industrial control and medical systems. The application program may also erase and/or program the flash while the application is running, allowing a great degree of flexibility for data storage field firmware upgrades, etc.

The Thumb set’s 16-bit instruction length allows it to approach twice the density of standard ARM code while retaining most of the ARM’s performance advantage over a traditional 16-bit processor using 16-bit registers. This is possible because Thumb code operates on the same 32-bit register set as ARM code. Thumb code is able to provide up to 65% of the code size of ARM, and 160% of the performance of an equivalent ARM processor connected to a 16-bit memory system. The particular flash implementation in the LPC2141/42/44/46/48 allows for full speed execution also in ARM mode. It is recommended to program performance critical and short code sections (such as interrupt service routines and DSP algorithms) in ARM mode. The impact on the overall code size will be minimal but the speed can be increased by 30% over Thumb mode. have been defined before or immediately following the equation. Use “(1)”, not “Eq. (1)” or “equation (1)”, except at the beginning of a sentence: “Equation (1) is . . .”

**Power supply**

In this project we have power supplies with +5V & -5V option normally +5V is enough for total circuit. Another (-5V) supply is used in case of OP amp circuit. Transformer primary side has 230/50HZ AC voltage whereas at the secondary winding the voltage is step downed to 12/50hz and this voltage is rectified using two full wave rectifiers. The rectified output is given to a filter circuit to filter the unwanted ac in the signal. After that the output is again applied to a regulator LM7805 (to provide +5v) regulator. Whereas LM7905 is for providing -5V regulation (+12V circuit is used for stepper motors, Fan and Relay by using LM7812 regulator same process like above supplies.) Do not use the word “essentially” to mean “approximately” or “effectively”. In your paper title, if the words “that uses” can accurately replace the word “using”, capitalize the “u”; if not, keep using lower-cased.

**ENERGY METER:**

- An electricity meter, electric meter, electrical meter, or energy meter is a device that measures the amount of electric energy

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**ARM7TDMI-S Processor Has Two Instruction Sets:**

The standard 32-bit ARM set.

- A 16-bit Thumb set.
consumed by a residence, a business, or an electrically powered device.

- Electric utilities use electric meters installed at customers’ premises to measure electric energy delivered to their customers for billing purposes. They are typically calibrated in billing units, the most common one being the kilowatt hour [kWh]. They are usually read once each billing period.

When energy savings during certain periods are desired, some meters may measure demand, the maximum use of power in some interval. "Time of day" metering allows electric rates to be changed during a day, to record usage during peak high-cost periods and off-peak, lower-cost, periods. Also, in some areas meters have relays for demand response load shedding during peak load periods.

GSM:

GSM (Global System for Mobile communication) is a digital mobile telephone system that is widely used in Europe and other parts of the world for transmitting mobile voice and data services. GSM uses a variation of Time Division Multiple Access (TDMA) and is the most widely used of the three digital wireless telephone technologies (TDMA, GSM, and CDMA). GSM digitizes and compresses data, then sends it down a channel with two other streams of user data, each in its own time slot. It operates at either the 900 MHz or 1,800 MHz frequency band. GSM was first introduced in 1991. As of the end of 1997, GSM service was available in more than 100 countries and has become the de facto standard in Europe and Asia.

3.1 What does GSM offer:

GSM supports voice calls and data transfer speeds of up to 9.6 kbit/s, together with the transmission of SMS (Short Message Service). GSM operates in the 900MHz and 1.8GHz bands in Europe and the 1.9GHz and 850MHz bands in the US. The 850MHz band is also used for GSM and 3G in Australia, Canada and many South American countries. By having a harmonized spectrum across most of the globe, GSM’s international roaming capability allows users to access the same services when travelling abroad as at home. This gives consumers seamless and same number connectivity in more than 218 countries. Terrestrial GSM networks now cover more than 80% of the world’s population. GSM satellite roaming has also extended service access to areas where terrestrial coverage is not available.

3.2 HISTORY:

In 1982, the European Conference of Postal and Telecommunications Administrations (CEPT) created the Group Special Mobile (GSM) to develop a standard for a mobile telephone system that could be used across Europe. In 1987, a memorandum of understanding was signed by 13 countries to develop a common cellular telephone system across Europe. Finally the system created by SINTEF lead by Torleiv Maseng was selected. In 1989, GSM responsibility was transferred to the European Telecommunications Standards Institute (ETSI) and phase I of the GSM specifications were published in 1990. The first GSM network was launched in 1991 by Radiolinja in Finland with joint technical infrastructure maintenance from Ericsson. By the end of 1993, over a million subscribers were using GSM phone networks being operated by 70 carriers across 48 countries.

3.3 GSM Frequencies:

GSM networks operate in a number of different frequency ranges (separated into GSM frequency ranges for 2G and UMTS frequency bands for 3G). Most 2G GSM networks operate in the 900 MHz or 1800 MHz bands. Some countries in the Americas (including Canada and the United States) use the 850 MHz and 1900 MHz bands because the 900 and 1800 MHz frequency bands were already allocated. Most 3G GSM networks in Europe operate in the 2100 MHz frequency band. The rarer 400 and 450 MHz frequency bands are assigned in some countries where these frequencies were previously used for first-generation systems.
GSM-900 uses 890–915 MHz to send information from the mobile station to the base station (uplink) and 935–960 MHz for the other direction (downlink), providing 124 RF channels (channel numbers 1 to 124) spaced at 200 kHz. Duplex spacing of 45 MHz is used. In some countries the GSM-900 band has been extended to cover a larger frequency range. This 'extended GSM', E-GSM, uses 880–915 MHz (uplink) and 925–960 MHz (downlink), adding 50 channels (channel numbers 975 to 1023 and 0) to the original GSM-900 band. Time division multiplexing is used to allow eight full-rate or sixteen half-rate speech channels per radio frequency channel. There are eight radio timeslots (giving eight burst periods) grouped into what is called a TDMA frame. Half rate channels use alternate frames in the same timeslot. The channel data rate for all 8 channels is 270.83 Kbit/s, and the frame duration is 4.615 ms. The transmission power in the handset is limited to a maximum of 2 watts in GSM850/900 and 1 watt in GSM1800/1900.

ARCHITECTURE:
The GSM network consists mainly of the following functional parts:

3.4.1 MSC:
The mobile service switching centre (MSC) is the core switching entity in the network. The MSC is connected to the radio access network (RAN); the RAN is formed by the BSCs and BTSs within the Public Land Mobile Network (PLMN). Users of the GSM network are registered with an MSC; all calls to and from the user are controlled by the MSC. A GSM network has one or more MSCs, geographically distributed.

16 * 2 Alphanumeric LCD

Liquid crystal display is very important device in embedded system. It offers high flexibility to user as he can display the required data on it. A liquid crystal display (LCD) is a thin, flat electronic visual display that uses the light modulating properties of liquid crystals (LCs). LCs do not emit light directly. LCDs therefore need a light source and are classified as "passive" displays. Here the LCD has different memories to display data, those are discussed below. Display data RAM (DDRAM) stores display data represented in 8-bit character codes. Its extended capacity is 80 X 8 bits, or 80 characters. The area in display data RAM (DDRAM) that is not used for display can be used as general data RAM. So whatever you send on the DDRAM is actually displayed on the LCD. For LCDs like 1x16, only 16 characters are visible, so whatever you write after 16 chars is written in DDRAM but is not visible to the user.

Figure below will show you the DDRAM addresses of 2 Line LCD.

SERIAL COMMUNICATION

INTRODUCTION

Computers transfer data in two ways: parallel and serial. In parallel data transfers, often 8 or more lines (wire conductors) are used to transfer data to a device that is only a few feet away. Examples of parallel transfers are printers and hard disks; each uses cables with many wire strips. Although in such cases a lot of data can be transferred in a short amount of time by using many wires in parallel, the distance cannot be great. To transfer to a device located many meters away, the serial method is used. In serial communication, the data is sent one bit at a time, in contrast to parallel communication, in which the data is sent a byte or more at a time. The 8051 has serial communication capability built into it, thereby making possible fast data transfer using only a few wires.

When a microprocessor communicates with the outside world, it provides the data in byte-sized chunks. In some cases, such as printers, the information is simply grabbed from the 8-bit data bus of the printer. This can work only if the cable is not too long, since long cables diminish and even distort signals. Furthermore, an 8-bit data path is expensive. For these reasons, serial communication is used for transferring data between two systems located at distances of hundreds of feet to millions of miles apart. The Figures shows serial versus parallel data transfers.
RELAY:
A relay is used to isolate one electrical circuit from another. It allows a low current control circuit to make or break an electrically isolated high current circuit path. The basic relay consists of a coil and a set of contacts. The most common relay coil is a length of magnet wire wrapped around a metal core. When voltage is applied to the coil, current passes through the wire and creates a magnetic field. This magnetic field pulls the contacts together and holds them there until the current flow in the coil has stopped. The diagram below shows the parts of a simple relay.

Figure: Relay

Operation:
When a current flows through the coil, the resulting magnetic field attracts an armature that is mechanically linked to a moving contact. The movement either makes or breaks a connection with a fixed contact. When the current is switched off, the armature is usually returned by a spring to its resting position shown in figure 6.6(b). Latching relays exist that require operation of a second coil to reset the contact position.

What's New in µVision4?
µVision3 adds many new features to the Editor like Text Templates, Quick Function Navigation, and Syntax Coloring with brace high lighting Configuration Wizard for dialog based startup and debugger setup. µVision3 is fully compatible to µVision4 and can be used in parallel with µVision4.

What is µVision4?
µVision3 is an IDE (Integrated Development Environment) that helps you write, compile, and debug embedded programs. It encapsulates the following components:
• A project manager.
• A make facility.
• Tool configuration.
• Editor.
  • A powerful debugger.

To help you get started, several example programs (located in the \C51\Examples, \C251\Examples, \C166\Examples, and \ARM\...\Examples) are provided.

• HELLO is a simple program that prints the string "Hello World" using the Serial Interface.
• MEASURE is a data acquisition system for analog and digital systems.
• TRAFFIC is a traffic light controller with the RTX Tiny operating system.
• SIEVE is the SIEVE Benchmark.
• DHRY is the Dhrystone Benchmark.
• WHETS is the Single-Precision Whetstone Benchmark.

Additional example programs not listed here are provided for each device architecture.

Building an Application in µVision4
To build (compile, assemble, and link) an application in µVision4, you must:
1. Select Project - (for example, 166\EXAMPLES\HELLO\HELLO.UV4).
2. Select Project - Rebuild all target files or Build target, µVision4 compiles, assembles, and links the files in your project.

CONCLUSION:
The project “WIRELESS ARM-BASED AUTOMATIC METER READING & CONTROL SYSTEM (WAMRCS)” has been successfully designed and tested. Integrating features of all the
hardware components used have developed it. Presence of every module has been reasoned out and placed carefully thus contributing to the best working of the unit. Secondly, using highly advanced IC’s and with the help of growing technology the project has been successfully implemented.

References
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