Attendance System by Face Recognition Using SIFT Algorithm and SMS Reporting to Parents Mobile Phone

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Abstract:

In this project an approach to the detection and identification of human faces is presented and then recognizes the person by comparing characteristics of the face to those of known individuals is described. And we introduced a new approach that give report by SMS to Authorized mobile.
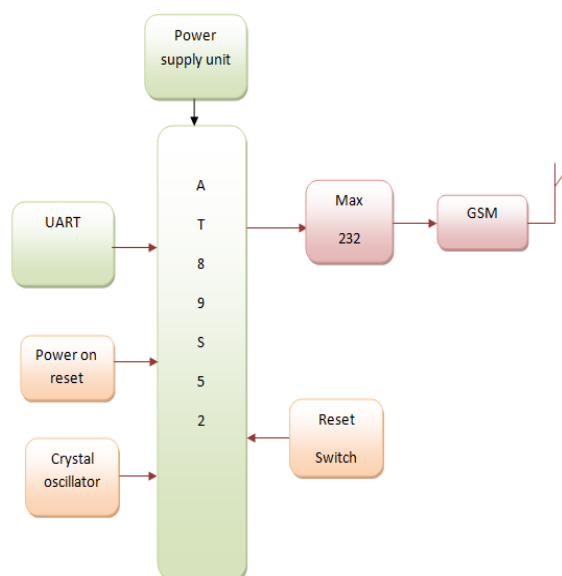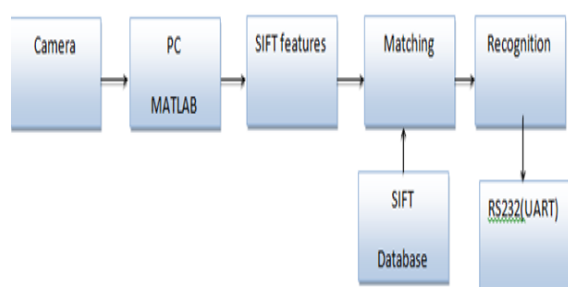
Scale Invariant Feature Transform:

Image matching is a fundamental aspect of many problems in computer vision, including object or scene recognition, solving for 3D structure from multiple images, stereo correspondence, and motion tracking. This paper describes image features that have many properties that make them suitable for matching differing images of an object or scene. The features are invariant to image scaling and rotation, and partially invariant to change in illumination and 3D camera viewpoint. They are well localized in both the spatial and frequency domains, reducing the probability of disruption by occlusion, clutter, or noise. Large numbers of features can be extracted from typical images with efficient algorithms. In addition, the features are highly distinctive, which allows a single feature to be correctly matched with high probability against a large database of features, providing a basis for object and scene recognition. The cost of extracting these features is minimized by taking a cascade filtering approach, in which the more expensive operations are applied only at locations that pass an initial test. Following are the major stages of computation used to generate the set of image features:

1. Scale-space extrema detection: The first stage of computation searches over all scales and image locations. It is implemented efficiently by using a difference-of-Gaussian function to identify potential interest points that are invariant to scale and orientation.

2. Keypoint localization: At each candidate location, a detailed model is fit to determine location and

scale. Keypoints are selected based on measures of their stability.

3. Orientation assignment: One or more orientations are assigned to each keypoint location based on local image gradient directions. All future operations are performed on image data that has been transformed relative to the assigned orientation, scale, and location for each feature, thereby providing invariance to these transformations.

4. Keypoint descriptor: The local image gradients are measured at the selected scale in the region around each keypoint. These are transformed into a representation that allows for significant levels of local shape distortion and change in illumination.

This approach has been named the Scale Invariant Feature Transform (SIFT), as it transforms image data into scale-invariant coordinates relative to local features. An important aspect of this approach is that it generates large numbers of features that densely cover the image over the full range of scales and locations. A typical image of size 500x500 pixels will give rise to about 2000 stable features (although this number depends on both image content and choices for various parameters). The quantity of features is particularly important for object recognition, where the ability to detect small objects in cluttered backgrounds requires that at least 3 features be correctly matched from each object for reliable identification. For image matching and recognition, SIFT features are first extracted from a set of reference images and stored in a database. A new image is matched by individually comparing each feature from the new image to this previous database and finding candidate matching features based on Euclidean distance of their feature vectors. This paper will discuss fast nearest-neighbor algorithms that can perform this computation rapidly against large databases. The keypoint descriptors are highly distinctive, which allows a single feature to find its correct match with good probability in a large database of features.

However, in a cluttered image, many features from the background will not have any correct match in the database, giving rise to many false matches in addition to the correct ones. The correct matches can be filtered from the full set of matches by identifying subsets of keypoints that agree on the object and its location, scale, and orientation in the new image.

Keypoint Localization:
Scale-space extrema detection produces too many keypoint candidates, some of which are unstable. The next step in the algorithm is to perform a detailed fit to the nearby data for accurate location, scale, and ratio of principal curvatures. This information allows points to be rejected that have low contrast (and are therefore sensitive to noise) or are poorly localized along an edge.
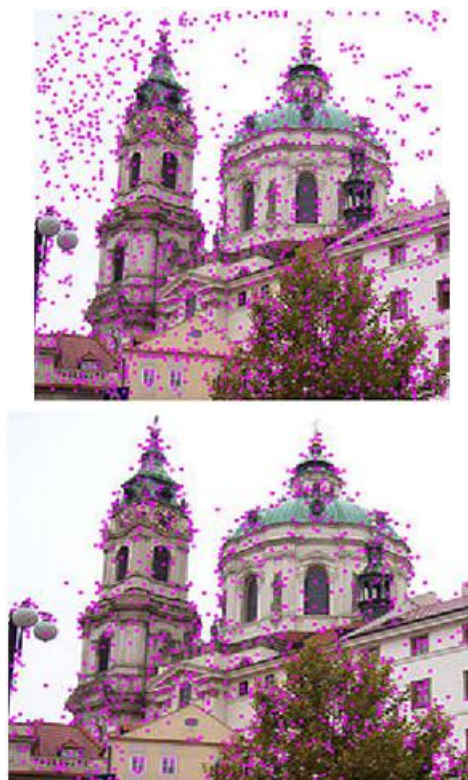
AT89S52 MICROCONTROLLER:
8052 is an 8-bit processor, meaning that the CPU can work on only 8 bits of data at a time.

Data larger than 8 bits has to be broken into 8-bit pieces to be processed by the CPU. 8052 is available in different memory types such as UV-EPROM, Flash and NV-RAM.

Serial Communication:

➢ MATLAB has an feature as External interface we connect MATLAB to any external electronic IC or communicate with any embedded system application.

➢ Using RS232 we will give the instructions to AT89S52 controller .

➢ Than controller operate the motors and sensors according the MATLAB instructions.

GSM:

MODEM SPECIFICATIONS:

The SIM300 is a complete Tri-band GSM solution in a compact plug-in module. Featuring an industry-standard interface, the SIM300 delivers GSM/GPRS900/1800/1900Mhz performance for voice, SMS, data and Fax in a small form factor and with low power consumption.

The leading features of SIM300 make it deal fir virtually unlimited application, such as WLL applications (Fixed Cellular Terminal), M2M application, handheld devices and much more.

1. Tri-band GSM/GPRS module with a size of 40x33x2.85
2. Customized MMI and keypad/LCD support
3. An embedded powerful TCP/IP protocol stack

Based upon mature and field proven platform, backed up by our support service, from definition to design and production.

Camera:

Schematic Diagram:
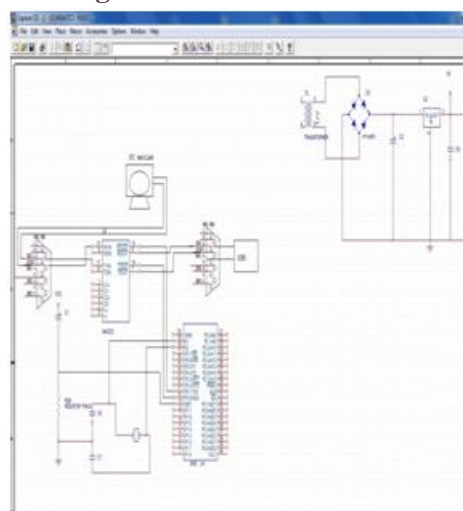
Conclusion:

Hence detection and identification of human faces is presented and then recognizes the person by comparing characteristics of the face to those of known individuals is described. Also SMS alerts are given to the authorized persons.

References:

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